

AMENDMENTS TO THE CLAIMS

This listing of claims replaces all prior versions of claims in the application.

1. (Currently amended): A reduction device of an industrial robot comprising:
 - a robot base installed in an XY plane of XYZ orthogonal coordinates;
 - a rotating barrel portion rotatably attached to the robot base;
 - a lower arm of which one end is axially supported by the rotating barrel portion via a front/rear shaft, pivoting back and forth to the robot base around the front/rear shaft;
 - a large gear fixed to the robot base, and
 - a small gear meshing with the large gear and axially supported in the rotating barrel portion,wherein a rotational center of the small gear is arranged within an angular range from the rotational center of the large gear, said angular range being ± 35 degrees from ~~an imaginary~~ a reference plane, and
- wherein said ~~imaginary~~ reference plane is defined as a plane parallel to a lower arm rotational plane, orthogonal to the front/rear shaft, and including a rotational axis of the large gear.

2. (Currently amended): A reduction device of an industrial robot comprising:
 - a robot base installed in an XY plane of XYZ orthogonal coordinates;
 - a rotating barrel portion rotatably attached to the robot base;

a lower arm of which one end is axially supported by the rotating barrel portion via a front/rear shaft, pivoting back and forth to the robot base around the front/rear shaft;

a small gear fixed to the robot base; and

a large gear meshing with the small gear and axially supported in the rotating barrel portion,

wherein a rotational center of the small gear is arranged within a angular range from the rotational center of the large gear, said angular range being ± 35 degrees from ~~an imaginary~~ a reference plane, and

wherein said ~~imaginary~~ reference plane is defined as a plane parallel to a lower arm rotational plane, orthogonal to the front/rear shaft, and including a rotational axis of the large gear.

3. (Currently amended): A reduction device of an industrial robot comprising:

a robot base installed in an XY plane of XYZ orthogonal coordinates;

a rotating barrel portion rotatably attached to the robot base to rotate around a rotating shaft;

a lower arm of which one end is axially supported by the rotating barrel portion;

an upper arm of which one end is axially supported by other end of the lower arm;

a large gear fixed to the lower arm; and

a small gear meshing with the large gear and axially supported in the rotating barrel portion,

wherein a rotational center of the small gear is arranged within an angular range from the rotational center of the large gear, said angular range being ± 35 degrees from ~~an imaginary~~ a reference plane, and

wherein said ~~imaginary~~ reference plane is defined as a plane parallel to a rotating barrel portion rotational plane, orthogonal to the rotating shaft, and including a rotational axis of the large gear.

4.-5. Canceled.

6. (Previously presented): The reduction device of an industrial robot according to any one of claims 1 through 3, characterized in that a center portion of the large gear includes a communication hole.